



C SDK Guide

Sybase Event Stream Processor

5.0

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Contents

Migration from Aleri Streaming Platform

The SDK interface provided by Sybase® Event Stream Processor (ESP) differs from the SDK interface provided in Aleri Streaming Platform (ASP). In Event Stream Processor, the SDK has been modified for improved flexibility and performance, and to accommodate projects running in a clustered environment.

Clusters and Projects

Because projects now run in a cluster, they are no longer accessed using the command and control host and port. A project has a unique identity denoted by its URI which typically consists of the cluster information, workspace name, and project name. The SDK takes care of resolving the URI to the physical address internally. The project object in ESP loosely corresponds to the platform object in ASP. There is no analogue of an ESP Server in the Pub/Sub API.

Note: There are methods to connect to a standalone project but these should not be used as they will be removed in a future release.

The ESP SDK includes new functionality to configure and monitor the cluster. There is no counterpart for these in the ASP Pub/Sub API.

Access Modes

In the ASP Pub/Sub, the Platform and Publisher objects were accessed using synchronous method calls. The Subscriber object required callback handlers. In ESP, this has changed. All entities—that is server, project, publisher, and subscriber—can be accessed using either DIRECT method calls or CALLBACK handlers. In addition, ESP introduces a third method called SELECTION access.

DIRECT access is similar to the way old Platform and old Publisher objects were called in ASP. Each call blocks until the task completes or results in an error. In ESP, you can use this mode for Subscribers too.

In CALLBACK, users register handler functions and the SDK calls the functions when anything of interest happens. This was the only way to work with subscribers in ASP. In ESP, you can optionally use this method for other entities too.

The SELECT access mode lets you register multiple entities with a selector and have a single thread wait for an event on any of those entities. Functionally, this is similar to the select/poll mechanism of monitoring multiple file descriptors in a single thread.

Automatic Reconnection and Monitoring

In ASP, the Pub/Sub API supported automatic reconnection to a peer when working in hot-active mode. ESP supports automatic reconnection but adds some additional functionality when working in CALLBACK or SELECT access modes. Additional functionality includes

Migration from Aleri Streaming Platform

checking if a cluster or project has gone down and optionally monitoring the backend for restarts.

Publishing

In DIRECT access mode, you can now optionally have the SDK spin a background thread when publishing to lead to better throughput. When using ASP, tasks such as these had to be done by the Pub/Sub user.

In ASP, a message was formatted using temporary storage (vectors) which needed to be filled in before calling the Pub/Sub API to create the buffer. In ESP, this is avoided by writing directly to a buffer. To create a message in the ESP SDK, users will indicate the start of a block or row, then populate it in sequence. The fields must be filled in the same order as they appear in the schema.

Subscribing

In ASP, the data from a message was available as a collection of objects. In the ESP SDK, that step is skipped. Methods are provided to read the buffer directly as native data types or helper objects (Money, BigDatetime, Binary). The data fields can be accessed in random order.

Entity Lifecycles and Access Modes

In the Sybase® Event Stream Processor C SDK, all entities exposed by the SDK have a common life cycle and multiple access modes.

User interaction in the Event Stream Processor (ESP) SDK is handled through entities the SDK exposes. The main entities are Server, Project, Publisher, and Subscriber. These entities correspond to the functional areas of the SDK. For example, the Server object represents a running instance of a cluster, the Project corresponds to a single project deployed to the cluster, the Publisher object deals with publishing data to a running project, and so on.

On initial retrieval, an entity is considered to be open. When an entity is open, you can retrieve certain static information about it. To accomplish its assigned tasks, an entity has to connect to the corresponding component in the cluster. A server connects to a running instance of a cluster, and EspProject, EspPublisher, and EspSubscriber all connect to running instances of a project in a cluster.

In the connected state, an entity can interact with the cluster components. Once an entity is disconnected, it can no longer interact with the cluster but is still an active object in the SDK, and can be reconnected to the cluster. Once an entity is closed, it is no longer available for interaction and is reclaimed by the SDK. To reuse an entity that has closed, retrieve a fresh copy of the entity.

For example, you can retrieve a Project object and connect it to a project in the cluster. If the back-end project dies, the SDK Project receives a disconnected event. You can attempt to reconnect manually, or, if you are using callback mode and your configuration supports it, the SDK tries to reconnect automatically. Upon successful reconnection, the SDK generates a connected event. If you actively close the entity, it disconnects from the back-end project and the SDK reclaims the Project object. To reconnect, you first need to retrieve a new Project object.

The SDK provides great flexibility in structuring access to the entities exposed by the API. There are three modes that can be used to access entities.

Direct	synchronous
Callback	asynchronous
Select	asynchronous

The default access mode in force whenever an entity is retrieved is direct. In this mode, all operations on an entity are synchronous. Once the call returns, the operation can be considered to be complete or an error has occurred.

In callback access, register a handler function with the entity. Most calls to the entity return immediately. Completion of the request is indicated by the generation of the corresponding event. The SDK has two internal threads to implement the callback mechanism. The update

Entity Lifecycles and Access Modes

thread monitors all entities currently registered for callbacks for applicable updates. If an update is found, an appropriate event is created and queued to the dispatch thread. The dispatch thread calls the registered handlers for the user code to process them.

The following example shows how an `EspProject` could be accessed in callback mode. If you are working in callback mode and want to receive the callback events, register your callback handlers before you call `connect` on the entity you are interested in:

```
    EspProjectOptions * options = esp_project_options_create(error);

    int rc = esp_project_options_set_access_mode(options,
CALLBACK_ACCESS, error);

    const char * temp = "esp://host.domain.com/workspace/project";
    EspUri * uri = esp_uri_create_string(temp, error);

    EspProject * project = esp_project_get(uri, NULL, options,
error);

    rc = esp_project_set_callback(project, ESP_PROJECT_EVENT_ALL,
project_callback, NULL, error);

    rc = esp_project_connect(project, error);

    //
    // The callback handler
    //
void project_callback(const EspProjectEvent * event, void * data)
{
    EspProject * project = NULL;
    const EspError * error = NULL;
    int rc;
    uint32_t type;
    rc = esp_project_event_get_type(event, &type, NULL);

    switch (type) {
        case ESP_PROJECT_EVENT_CONNECTED:
            project = esp_project_event_get_project(event, NULL);
            break;
        case ESP_PROJECT_EVENT_DISCONNECTED:
            project = esp_project_event_get_project(event, NULL);
            esp_project_close(project, NULL);           // you can
call close inside a callback
            break;
        case ESP_PROJECT_EVENT_CLOSED:
        case ESP_PROJECT_EVENT_STALE:
        case ESP_PROJECT_EVENT_UPTODATE:
            break;
        case ESP_PROJECT_EVENT_ERROR:
            error = esp_project_event_get_error(event, NULL);
            break;
    }
}
```


The select access mode lets you multiplex various entities in a single thread—somewhat similar to the select and poll mechanisms available on many systems—to monitor file descriptors. An entity is registered with an `EspSelector` together with the events to monitor for. Then call `esp_selector_select(...)` which blocks until a monitored update occurs in the background. The function returns a list of `EspEvent` objects. First determine the category (server, project, publisher, subscriber) of the event, then handle the appropriate event type. In select mode, the SDK uses one background update thread to monitor for updates. If detected, the appropriate event is created and pushed to the `EspSelector`. The event is then handled in your own thread.

The following example uses a single selector to multiplex different entities.

```
// Assuming the EspServer, EspProject, EspPublisher, EspSubscriber
// have been created with the correct options
// Not doing error checking, etc for clarity

    EspSelector * selector = esp_selector_create("server-select",
error);
    rc = esp_server_select_with(server, selector,
ESP_SERVER_EVENT_ALL, error);
    EspList * list = esp_list_create(ESP_LIST_EVENT_T, error);

    rc = esp_server_connect(m_server, error);

    uint32_t type;
    const void * ev;
    int c;
    int done = 0;

    while (!done)
    {
        esp_list_clear(list, error);
        rc = esp_selector_select(selector, list, error);

        c = esp_list_get_count(list, error);

        for (int i = 0; i < c; i++)
        {
            ev = esp_list_get_event(list, i, error);

            int cat = esp_event_get_category(ev, error);

            switch ( cat ) {
                case ESP_EVENT_SERVER:
                    srvevent = (EspServerEvent*) ev;
                    esp_server_event_get_type(srvevent, &type, error);
                    switch (type) {
                        // process server events
                        case ESP_SERVER_EVENT_CONNECTED:
                            break;
                        // .....
                    }
                default:
                    break;
            }
        }
    }
}
```


Publishing

The SDK provides several options for publishing data to a project.

The steps involved in publishing data are:

1. Create an `EspPublisher` for the project to publish to. You can create an `EspPublisher` directly or from a previously retrieved and connected `EspProject` object.
2. Create an `EspMessageWriter` for the stream to publish to. You can create multiple `EspMessageWriters` from a single `EspPublisher`.
3. Create an `EspRelativeRowWriter`.
4. Format the data buffer to publish using `EspRelativeRowWriter` methods.
5. Publish the data.

While `EspPublisher` is thread safe, `EspMessageWriter` and `EspRelativeRowWriter` are not. Therefore, ensure that you synchronize access to the latter two.

The SDK provides a number of options to tune the behavior of an `EspPublisher`. Specify these options using `EspPublisherOptions` when creating the `EspPublisher`. Once created, options cannot be changed. Like all other entities in the SDK, publishing also supports the direct, callback, and select access modes.

In addition to access modes, the SDK supports internal buffering. When publishing is buffered, the data is first written to an internal queue. This is picked up by a publishing thread and then written to the platform. Buffering is possible only in direct access mode. Direct and buffered publishing potentially provides the best throughput.

Two other settings influence publishing: batching mode and sync mode. Batching controls how data rows are written to the socket. They can be written individually or grouped together in either envelope or transaction batches. Envelopes group individual rows together to send to the platform and are read together from the socket by the platform. This improves network throughput. Transaction batches, like envelope batches, are also written and read in groups. However, with transaction batches, the platform only processes the group if all the rows in the batch are processed successfully. If one fails, the whole batch is rolled back

Note: When using shine-through to preserve previous values for data that are null in an update record, publish rows individually or in envelopes, rather than in transaction batches.

Sync mode settings control the publishing handshake between the SDK and the platform. By default, the SDK keeps sending data to the platform without waiting for acknowledgement. But if sync mode is set to true, the SDK waits for acknowledgement from the platform before sending the next batch of data. This provides an application level delivery guarantee, but it reduces throughput.

There are certain considerations to keep in mind when using callback or select mode publishing. These modes are driven by the `ESP_PUBLISHER_EVENT_READY` event,

which indicates that the publisher is ready to accept more data. In response, you can publish data or issue a commit, but only one such action is permitted in response to a single `ESP_PUBLISHER_EVENT_READY` event.

Publishing in async mode improves throughput, but does not provide an application level delivery guarantee. Since TCP does not provide an application level delivery guarantee either, data in the TCP buffer could be lost when a client exits. Therefore, a commit must be executed before a client exit when publishing in async mode.

In general terms, the return code from a Publish call indicates whether or not the row was successfully transmitted. Any error that occurs during processing on the platform (such as a duplicate insert) will not get returned. The precise meaning of the return code from a Publish call depends on the access mode and the choice of synchronous or asynchronous transmission.

When using callback or select access mode, the return only indicates whether or not the SDK was able to queue the data. The indication of whether or not the data was actually written to the socket will be returned by the appropriate event. The callback and select access modes do not currently support synchronous publishing.

When using direct access mode, the type of transmission used determines what the return from the Publish call indicates. If publishing in asynchronous mode, the return only indicates that the SDK has written the data to the socket. If publishing in synchronous mode, the return from the Publish call indicates the response code the platform sent.

In no case will errors that occur during processing on the platform (such as a duplicate insert) be returned by a Publish call.

Like all entities, if you intend to work in callback mode with a Publisher and want to get notified, register the callback handler before the event is triggered. For example:

```
esp_publisher_options_set_access_mode(options, CALLBACK_ACCESS,
error);
esp_publisher_set_callback(publisher, events, callback, NULL, error)
esp_publisher_connect(publisher, error);
```

The following code snippets illustrate different ways of publishing data.

The first example shows publishing in direct access mode with transaction blocks.

```
publisher = esp_project_create_publisher(project, NULL, error);
// create publisher with default options from an
existing EspProject
int rc = esp_publisher_connect(publisher, error);
// connect the publisher
const EspStream * stream = esp_project_get_stream(project,
"Stream1", error);
// retrieve EspStream we want to publish to
const EspSchema * schema = esp_stream_get_schema(stream, error);
// determine its schema
EspMessageWriter * writer = esp_publisher_get_writer(publisher,
stream, error);
// create EspMessageWriter to publish to "Stream1"
EspRelativeRowWriter * row_writer =
```

```

esp_message_writer_get_relative_rowwriter(writer, error);

    int32_t numcols;
    esp_schema_get_numcolumns(schema, &numcols, error);      //
number of columns in "Stream1"

    int32_t intvalue = 10;
    bool inblock = false;

    while (...) {
        // your logic to determine how
long to publish
        if (!inblock) {
            // your logic to determine if to
start a transaction
            esp_message_writer_start_transaction(writer, 0, NULL);
            inblock = true;
        }
        esp_relative_rowwriter_start_row(row_writer, NULL);    //
start a data row
        int32_t coltype;

        for (int i = 0; i < numcols; ++i) {
            esp_schema_get_column_type(schema, i, &coltype, error);
            switch (coltype) {
                case ESP_DATATYPE_INTEGER:
                    esp_relative_rowwriter_set_integer(row_writer,
intvalue++, error);
                    break;
                // ...
                // Code to fill in other data types goes here ....
                // ...
                // NOTE - you must fill in all data fields, with NULLs
is needed
                default:
                    esp_relative_rowwriter_set_null(row_writer, error);
                    break;
            }
        }
        esp_relative_rowwriter_end_row(row_writer,
error);                // end the data row

        if ((nrows % 60) == 0) {
            // determine if the batch is to be ended, we code
for 60 rows per block
            esp_message_writer_end_block(writer, error);
            // end the batch started in
            esp_message_writer_start_transaction()
            esp_publisher_publish(publisher, writer,
error);                // publish the batch
            inblock = false;
        }
    }
    esp_publisher_close(publisher, error);                    //
done with publishing

```

This example shows publishing in callback access mode.

```

int rc;
EspPublisherOptions * options =
esp_publisher_options_create(error);
    // create EspPublisherOptions
rc = esp_publisher_options_set_access_mode(options,
CALLBACK_ACCESS, error);
    // set access mode
publisher = esp_project_create_publisher(project, options,
error);
    // create EspPublisher using the options above from
existing EspProject
    esp_publisher_options_free(options, error); //
free EspPublisherOptions
rc = esp_publisher_set_callback(publisher,
ESP_PUBLISHER_EVENT_ALL, publish_callback,
NULL, m_error); // set callback handler
rc = esp_publisher_connect(publisher, error); //
connect publisher

...
...
...

// Handler function
void publish_callback(const EspPublisherEvent * event, void *
user_data)
{
    EspPublisher * publisher = NULL;
    EspMessageWriter * mwriter = NULL;
    EspRelativeRowWriter * row_writer = NULL;
    EspProject * project = NULL;
    const EspStream * stream = NULL;
    const EspSchema * schema = NULL;

    EspError * error = esp_error_create();

    int rc;
    uint32_t type;

    publisher = esp_publisher_event_get_publisher(event, error);
    rc = esp_publisher_event_get_type(event, &type, error);

    switch (type)
    {
        case ESP_PUBLISHER_EVENT_CONNECTED:
            // EspProject, EspStream, EspSchema can be retrieved
from the EspPublisherEvent
            // if required
            project = esp_publisher_get_project(publisher, error);
            stream = esp_project_get_stream(project, "Stream1",
error);
            schema = esp_stream_get_schema(stream, error);
            break;

        case ESP_PUBLISHER_EVENT_READY:

```

```
        // populate EspMessageWriter with data to publish
        rc = esp_publisher_publish(publisher, mwriter, error);
        break;

    case ESP_PUBLISHER_EVENT_DISCONNECTED:
        esp_publisher_close(publisher, error);
        break;

    case ESP_PUBLISHER_EVENT_CLOSED:
        break;
}

if (error)
    esp_error_free(error);
}
```


Subscribing

The SDK provides various options for subscribing to a project.

Subscribing to data using the SDK involves the following steps:

1. Create an `EspSubscriber` object. This can be created directly or retrieved from `EspProject`.
2. Connect the `EspSubscriber`.
3. Subscribe to streams.
4. In direct access mode, retrieve events using `esp_subscriber_get_next_event()`. In callback and select access modes, the event is generated by the SDK and passed back to user code.
5. For data events, retrieve `EspMessageReader`. This encapsulates a single message from the platform. It may consist of a single data row or a transaction/envelope block with multiple data rows.
6. Retrieve one or more `EspRowReaders`. Use the methods in `EspRowReader` to read in individual fields.

This example shows subscribing to a stream using direct access mode with default options:

```

EspError * error = esp_error_create();
esp_sdk_start(error);
EspUri * project_uri = esp_uri_create_string("esp://server:port//
default/vwap", error);
EspProject * project = esp_project_create(project_uri, NULL, NULL,
error);
rc = esp_project_connect(project, error);
EspSubscriber * subscriber = esp_project_create_subscriber(project,
NULL, error);
rc = esp_subscriber_connect(subscriber, error);

EspStream * stream = esp_project_get_stream(project, "Trades",
error);
rc = esp_subscriber_subscribe(subscriber, stream, error);

while (true) {
    EspSubscriberEvent * event =
    esp_subscriber_get_next_event(subscriber, error);

    // process event data

    // delete event
    esp_subscriber_event_free(event);
}

esp_subscriber_close(subscriber, error);
esp_sdk_close();

```

If the event is an `ESP_SUBSCRIBER_EVENT_DATA` event, it contains field data. This is a typical example of reading data from a subscribe event:

Subscribing

```
    const EspStream * stream = esp_subscriber_event_get_stream(event,
error);
    // stream for this event
    EspMessageReader * reader =
esp_subscriber_event_get_reader(event, error);
    // get message reader
    int rc = esp_message_reader_is_block(reader, &flag,
error);
    // you can check if this a block
    const EspSchema * schema = esp_stream_get_schema(stream,
error);
    // get the stream schema if you do not have it
    EspRowReader * row_reader;

    int32_t int_value;
    int numcolumns = 0, numRows = 0;
    int type;
    rc = esp_schema_get_numcolumns(schema, &numcolumns,
error);
    // need to know how many columns are there

    while ((row_reader = esp_message_reader_next_row(reader,
error)) != NULL) {
        // loop until we finish all rows
        for (int i = 0; i < numcolumns; ++i) {
            rc = esp_row_reader_is_null(row_reader, i, &flag,
error);
            // if column is null, skip
            if ( flag )
                continue;
            rc = esp_schema_get_column_type(schema, i, &type, error);
            switch ( type ) {
                case ESP_DATATYPE_INTEGER:
                    rc = esp_row_reader_get_integer(row_reader, i,
&int_value, error);
                    break;
                case ESP_DATATYPE_LONG:
                    rc = esp_row_reader_get_long(row_reader, i,
&long_value, error);
                    break;
                case ESP_DATATYPE_FLOAT:
                    rc = esp_row_reader_get_float(row_reader, i,
&double_value, error);
                    // ...
                    // other data types
                    // ...
            }
        }
    }
}
```

Failover Handling

The SDK supports either fully transparent or automatic failover in a number of situations.

- **Cluster failovers** – the URIs used to connect to a back-end component can include a list of cluster manager specifications. The SDK maintains connections to these transparently. So, if any one manager in the cluster goes down, the SDK tries to reconnect to another instance. The SDK returns an error only if connections to all known instances fail. If working in callback or select access modes, you can configure the SDK with an additional level of tolerance for loss of connectivity. In this case, the SDK does not disconnect an EspServer instance even if all known manager instances are down. Instead, it generates an `ESP_SERVER_EVENT_STALE` event. If it manages to reconnect after a (configurable) number of attempts, it generates an `ESP_SERVER_EVENT_UPTODATE`. Otherwise, it disconnects and generates an `ESP_SERVER_EVENT_DISCONNECTED` event.
- **Project failovers** – an Event Stream Processor cluster allows a project to be deployed with failover. Based on the configuration settings, a cluster restarts a project if it detects that it has exited (however, projects are not restarted if they are explicitly closed by the user). To support this, you can have EspProject instances monitor the cluster for project restarts and then reconnect. This works only in callback or select modes. An `ESP_PROJECT_EVENT_STALE` event is generated when the SDK detects that the project has gone down. If it is able to reconnect, it generates an `ESP_PROJECT_EVENT_UPTODATE` event. Otherwise, it generates an `ESP_PROJECT_EVENT_DISCONNECTED` event.
- **Active-active deployments** – you can deploy a project in active-active mode. In this mode, the cluster starts two instances of the project, a primary instance and a secondary instance. Any data published to the primary instance is automatically mirrored to the secondary instance. The SDK supports such active-active deployments. When connected to an active-active deployment, if the currently connected instance goes down, EspProject tries to reconnect to the alternate instance. Unlike failovers, this happens transparently. Therefore, if the reconnection is successful, there is no indication generated to the user. In addition to EspProject, there is support for this mode when publishing and subscribing. If subscribed to a project in an active-active deployment, the SDK does not disconnect the subscription if the instance goes down. Instead, it generates an `ESP_SUBSCRIBER_EVENT_DATA_LOST` event. It then tries to reconnect to the peer instance. If it is able to reconnect, the SDK resubscribes to the same streams. Subscription clients then receive an `ESP_SUBSCRIBER_EVENT_SYNC_START` event, followed by the data events, and finally an `ESP_SUBSCRIBER_EVENT_SYNC_END` event. Clients can use this sequence to maintain consistency with their view of the data if needed. Reconnection during publishing is also supported but only if publishing in synchronous mode. It is not possible for the SDK to guarantee data consistency otherwise. Reconnection during publishing happens transparently; there are no external user events generated.

API Reference

Detailed information on methods, functions, and other programming building blocks is provided in the API documentation download.

Download and install the *C API documentation* to your local machine.

When the download is complete:

1. Extract the files to the desired location on your local machine.
2. Browse to the location where you extracted the files.
3. Launch `index.html` to view the API documentation.

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